

**TS-2200 User's Manual**





Technologic Systems, Incorporated

16610 East Laser Drive, Suite 10  
Fountain Hills, AZ 85268

480-837-5200

FAX 837-5300

[info@embeddedx86.com](mailto:info@embeddedx86.com)

<http://www.embeddedx86.com/>

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## Limited Warranty

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## 1 Introduction

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The model TS-2200 is a compact, full-featured PC compatible Single Board Computer based on the 386EX processor. If you are coming up from the 8-bit microcontroller world, you will find that this product provides much more performance and much quicker development since you can now use standard PC development tools such as Turbo C or Quick Basic. If you have done work in the PC world in the past, you will find you can now build applications for a very small target that does not require a keyboard, video, floppy disks, or hard drives.

You can typically write and debug code on a host PC using standard development tools for the PC platform, then simply copy it to and run it on the TS-2200 without modification. If additional peripherals are required, the PC/104 expansion bus allows for many standard functions available off-the-shelf. It is also very simple to create a custom PC/104 daughter board for those special features that differentiate your product. Technologic Systems can provide technical support as well as a free quotation for any custom hardware, software, or BIOS modifications you may require.

This manual is fairly short. This is because for the most part, the TS-2200 is a standard 80386 based PC compatible computer, and there are hundreds of books about writing software for the PC platform. The purpose of this manual is documenting where the TS-2200 differs from a standard PC.

## 2 PC Compatibility

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PC compatibility requires much more than just a 386 processor. It requires PC compatible memory and I/O maps as well as a PC compatible BIOS. The General Software EMBEDDED BIOS offers a high degree of compatibility with past and present BIOS standards allowing it to run off-the shelf operating systems and application software.

The EMBEDDED BIOS has been tested with all major versions of DOS, including MS-DOS, DR-DOS, and Embedded DOS 6-XL; all major versions of OS/2, including MS-OS/2 and IBM OS/2; MS-Windows 3.1, Windows-95, Windows NT, and NetWare 386.

Technologic Systems Embedded PCs are compatible with a wide variety of x86 based operating systems. A partial list OSeS currently used with our boards by customers includes:

- GNU/Linux, kernel versions 1.0.x, 2.0.x, and 2.2.x
- TNT Embedded Toolsuite, Phar Lap Software
- RTKernel, On Time Software
- RTEMS, On-Line Applications Research Corporation
- DOS with Waterloo TCP (WATTCP), public domain TCP/IP source code for DOS

## 3 Power

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The TS-2200 requires **regulated** +5VDC at 650mA (typical). A quick release screw-down terminal block for the +5V power and power GND connections is provided for easy connection to an external power supply.

When power is first supplied to the TS-2200, the board mounted LED (labeled D2) is immediately turned on under hardware control. Once the processor begins execution, the LED is turned off under software control. If the LED does not turn on at all, the most likely problem is the power supply. Check that the +5V and GND connections are not reversed. A diode protects the board against damage in such a situation, but it will not run.

Please note that supply voltages over +6VDC may damage the TS-2200. Be sure to use a **regulated** +5VDC power supply.

## 4 Memory

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### 4.1 DRAM

The TS-2200 has a total of 2 Megabytes of DRAM providing 640 KB of base memory, 1 Megabyte of extended memory, and 128 KB of shadow RAM for the BIOS and DOS-ROM. This is identical to a standard PC memory map. The Flash SSD is the exception -- see below for details.

As shipped, the 1 Megabyte of extended memory is used as a RAM disk by the `vdisk.sys` device driver. The RAM disk is accessible as drive C: if the DiskOnChip Flash disk is **not** installed, drive D: if it **is**. The size of the disk can be reduced to provide extended memory for an application (or simply removed entirely) by editing the CONFIG.SYS file in the root directory of drive A:.

### 4.2 Flash

There is a total of 1 MB of Flash memory on the TS-2200. The top 128 KB of Flash are reserved for the BIOS and DOS-ROM. During POST, they are copied from Flash into DRAM at addresses E0000h through FFFFFh for improved performance (a standard technique known as BIOS Shadowing). The remainder of the Flash memory (896 KB) is used by a SSD (solid state disk) appearing as drive A. The SSD is fully supported by the BIOS as an INT 13h drive.

The physical Flash memory is accessed by the BIOS through a 64 KB memory mapped window at addresses D0000h through DFFFFh. If you are installing a PC/104 daughter card that uses memory mapped I/O, it must not conflict with this address range.

The Flash memory is guaranteed capable of a minimum of 100,000 write/erase cycles. This means that if you completely erase and rewrite the SSD drive 10 times a day you have over 27 years before any problems would occur. Reading the SSD produces no wear at all.

### 4.3 Flash Expansion

If 896 KB of Flash is insufficient for your application, an empty 32-pin socket is available for Flash expansion using an M-Systems DiskOnChip 2000 or DiskOnChip Millennium Flash Drive. This product is a wonder of miniaturization; it is a complete Flash SSD in a single 32 pin package currently available in sizes from 4 MB up to 144 MB. The DiskOnChip is available from Technologic Systems as well as other distributors. It is compatible with DOS as shipped, and drivers for other operating systems are available.

When using the DiskOnChip, it will simply appear as drive C: The DiskOnChip is accessed through an 8 KB range of CE000h through CFFFFh in memory space. If you are installing a PC/104 daughter card that uses memory mapped I/O, it must not conflict with this address range if the DiskOnChip is installed. Additionally, the DiskOnChip firmware uses approximately 20 KB of user RAM (below 640 KB).

### 4.4 Battery-Backed SRAM

The 32-pin socket can also optionally hold 32 KB of battery-backed CMOS SRAM memory. This or the DiskOnChip may be installed, but not both.

Battery backed SRAM provides non-volatile memory with unlimited write cycles and no write time degradation, unlike Flash memory. The SRAM uses an additional 32 KB range of C8000h through CFFFFh. If the SRAM is installed, PC/104 daughter card that uses memory mapped I/O must not conflict with this address range.

The SRAM can be utilized as a RAM disk (drive C:) by the `TSRAMDSK.SYS` device driver. The device driver can be added or removed (and the SRAM accessed directly) by editing the associated line in the `CONFIG.SYS` file in the root directory of drive A:. Please see the *BIOS/DOS User's Manual* for further information on `TSRAMDSK.SYS`.

I/O 75h, bit 0 can be read to determine whether the SRAM option is installed; a '1' in bit 0 indicates that it is installed, a '0' that it is not.

## 5 Serial Ports

The two PC compatible asynchronous serial ports provide a means to communicate with external serial devices such as printers, modems, etc. Each is independently configured as a standard PC COM port which is compatible with the National Semiconductor NS16C450. COM1 appears in the I/O space at 3F8h – 3FFh and uses IRQ4. COM2 is located at 2F8h – 2FFh and uses IRQ3.

The COM ports use a master clock of 1.8519 MHz as compared to a standard clock of 1.8432 MHz. This results in an error for all baud rates of .0047 (less than 1/2%). The error is insignificant and this clock value allows standard baud rate selections -- for example a divisor of 12 yields 9600 baud.

By changing an internal configuration register in the 386EX, the serial clock can be switched to 12.5 MHz (the processor clock divided by 2). This feature allows baud rates higher than 115 Kbaud (up to 781 Kbaud), as well as low error, non-standard lower baud rates (such as 24 Kbaud). See Appendix F for further information.

The COM ports may also be configured to use a DMA channel, which is handy when very high baud rates are being used. When enabled, a DMA request is issued any time a serial port's receive buffer is full or its transmit buffer is empty. This allows higher speed operation with much lower CPU overhead. See the Intel 386EX User's Manual for further details.

### 5.1 Serial Port Configuration Registers

Because both serial ports are 100% PC compatible, software written for the PC that accesses serial ports directly or through standard BIOS calls will work without modification on the TS-2200. The details of the COM port internal registers are available in most PC documentation books or the data sheet for the National Semiconductor NS16C450 may be consulted.

### 5.2 Serial Port Hardware

Each serial port has 4 lines buffered: the two data lines and the CTS / RTS handshake pair. This is quite sufficient to interface with the vast majority of serial devices. The serial lines are routed to 10 pin headers labeled COM1 and COM2. A serial adapter cable can be plugged into the header to convert this into a standard DB9 male connector. The pin out for the 10 pin header and DB9 male connector are listed below. The RTS signal also drives the DTR pin on the serial ports; DTR is always the same state as RTS. In addition, RTS is also used to enable the RS-485 transmitter (see below for more details).

	NC	10	5	GND	
	NC	9	4	DTR (RTS)	[out]
[in]	CTS	8	3	TX data	[out]
[out]	RTS	7	2	RX data	[in]
	NC	6	1	NC	

Figure 1 - Serial Port Header and DB9 Pin-out [signal direction is in brackets]

**PLEASE NOTE:** The serial port headers use a non-standard numbering scheme. This was done so the header pins would have the same numbering as the corresponding DB-9 pin; i.e. pin 8 (CTS) on the header connects to pin 8 on the DB-9

### 5.3 RS-485 / RS-422 Support

An option is available to add support to COM1 for half or full-duplex RS-485. RS-485 drivers allow communications between multiple nodes up to 4000 feet (1200 meters) via twisted pair cable. Half-duplex RS-485 requires one twisted pair plus a Ground connection, while full-duplex RS-485 (also known as RS-422) requires two twisted pairs plus a Ground connection.

For half-duplex operation, a single twisted pair is used for transmitting and receiving. The serial port's RTS signal controls the RS-485 transmitter/receiver (see next section for automatic operation). When RTS is asserted true (bit 1 of the modem control register = 1), the RS-485 transmitter is enabled and the receiver disabled. When RTS is de-asserted the transmitter is tri-stated (disabled) and the receiver is enabled. Since the transmitter and receiver are never both enabled, the serial port UART does not receive the data transmitted. The transmitter and receiver share a single pair of signals that are

available in a screw-down terminal block. See the table below for pin-outs **Note:** the correct jumper must be installed. See the next table for details.

Position (with terminal strip facing you)	Left	Center	Right
Silk-screen Label	TX+	TX- GND	RX- RX+
Half-duplex Usage	TX+ / RX+	TX- / RX- GND	Not Used Not Used
Full-duplex Usage	TX+	TX- GND	RX- RX+

Table 1 - RS-485 Signals

For full duplex (RS-422) operation, a twisted pair is used for receiving and another twisted pair is used for transmitting. The RS-485 transmitter is typically enabled continuously (RTS asserted), since the separate transmit and receive twisted pairs remove problems with data loop-back. The full-duplex receiver inputs are available on the terminal block (see the table above). **Note:** the correct jumper must be installed - see the table below for details.

Fail-safe bias resistors are used to bias both the TX pair and the RX pair to the correct state when these pairs are not being actively driven. This is an important consideration, since in a typical RS-485 installation, the drivers are frequently tri-stated. If fail-safe bias resistors are not present, the 485 bus will be floating and very small amounts of noise can cause spurious characters at the receivers. A 1.2 KOhm resistor is used to pull the TX+ signal to 5V and another 1.2 KOhm resistor pulls the TX- signal to ground. The RX+ and RX- signals are biased in the same manner. Termination resistors are also required for reliable operation particularly when running long distances. Termination resistors should only be installed at each end of a RS-485 transmission line pair. In a multi-drop application where there are several drivers and/or receivers attached, only the devices at each end of the transmission line pair should have termination resistors.

Installing **JP4** adds a 100 Ohm termination resistor to the RX pair while **JP5** adds a 100 Ohm termination resistor to the TX pair.

When the RS-485 option is installed, jumpers **JP6 and JP7** select which receiver is fed to the COM1 UART. Only one (or neither) of these jumpers should be installed at a time!

A read at I/O location 76h bit 0 will return a "1" when the RS-485 option is installed.

### 5.4 Automatically Enabled RS-485

In most RS-485 applications, the transmitter is enabled while sending data and disabled (tri-stated) when not. This allows for an inexpensive 'network' of multiple devices, all using a single twisted pair to communicate. Enabling and disabling the RS-485 transmitters can be done in software by asserting and deasserting RTS. This can be difficult to implement and bug prone.

#### RS-485 Quick start procedure:

1. The RS-485 option must be installed
2. Install JP6 or JP7 to enable Half or Full duplex RS-485 operation
3. Attach the RS-485 cable to the 5-pin terminal strip connector.
4. Set the COM1 UART serial parameters (baud rate, data, parity, and stop bits, interrupts, etc).
5. To transmit data, assert RTS and write the data to the UART
6. To receive data, deassert RTS and read the data from the UART

Jumper	Receiver Source
JP6	Full-duplex RS-485
JP7	Half-duplex RS-485
neither	RS-232

Table 3 - COM1 Receiver Source

I/O Address	R / W	Bit 0 Description
76h	Read	RS-485 option 0 = Not installed 1 = Option installed
76h	Write	RS-485 control 0 = use RTS enabled RS-485 1 = enable automatic RS-485
77h	Read	Returns status of TX485EN pin

Table 2 – TS-2100 Control Registers – All signals are R/W through bit 0 of the address



A simpler method implemented on the TS-2200 utilizes Timer 2 in the i386EX to keep track of the bits shifting out of the UART. It automatically turns on the transmitter, waits for the character to be sent, then turns off the transmitter. The timer is simply initialized once based on baud rate and data format. This totally eliminates the software overhead of controlling the RTS line manually.

To activate automatic transmitter enable, I/O location 76h bit 0 must be set to a "1", and Timer 2 initialized. When I/O location 76h bit 0 is set to "0", user software uses the RTS line to control the RS-485 transmitter. (Set RTS, and the transmitter is enabled. Clear RTS, and it is disabled.)

To initialize Timer 2, a value of 0B2h must be written to I/O location 043h, then a 16 bit count must be written to I/O location 042h as two consecutive bytes with least significant byte first. The count is determined by the following equation:

$$\text{Count} = [16 * (\text{Baud Divisor}) * (\text{Bits/Character})] - 2$$

For example, for 9600 baud, 8 data, no parity, 1 stop bit:

Baud divisor = 12

Bits/Character = 1 start bit + 8 data bits + 0 parity bits + 1 stop bit = 10

Count = [16 \* 12 \* 10] - 2 = 1918 decimal = 077Eh

The instructions in x86 assembly would then be:

```

MOV    AH, 0B2h
OUT    043h, AH    ; Set timer2 mode to one-shot
MOV    AH, 07Eh
OUT    042h, AH    ; load timer2 LSB
MOV    AH, 07h
OUT    042h, AH    ; load timer2 MSB
    
```

Serial Format	Formula	Result (decimal)	MSB	LSB
9600, No parity, 8 Data, 1 Stop	[16 * 12 * 10] - 2 =	1918	07h	7Eh
19200, No parity, 7 Data, 1 Stop	[16 * 6 * 9] - 2 =	862	03h	5Eh
9600, Even parity, 8 Data, 2 Stop	[16 * 12 * 12] - 2 =	2302	08h	0FEh
2400, Space parity, 8 Data, 1 Stop	[16 * 48 * 11] - 2 =	8446	20h	0FEh

Table 4 - Auto Enabled RS-485 Examples

**Note:** These equations assume the standard 1.85 MHz clock is being used for baud rate generation. If the 12.5 MHz clock is being used (see Appendix F) these equations must be modified. Contact Technologic Systems for details.

### 5.5 Adding Serial Ports

If your project requires more than two serial ports, additional ports may be added via the PC/104 expansion bus. Technologic Systems currently offers a 2 serial / 1 parallel port card, and other manufacturers sell cards with up to four additional serial ports. Typically these would be configured as COM3 or COM4 or be assigned other non-standard I/O locations. Because DOS only directly supports four serial ports, any additional ports beyond four will require software drivers.

The PC/104 bus has IRQ3, 4, 5, 6, 7 or 9 available for additional serial ports. If IRQ3 or 4 are to be used on a PC/104 expansion card, then care must be taken since COM2 and COM1 also use these IRQs, respectively. For example, if IRQ4 is used for COM3 then either COM1 must be used in a non-interrupt fashion or only one COM port can have the interrupt enabled at a time. In any case only one COM should have the Interrupt Enable (Bit 3 of Modem Control Reg.) set at any one time if they share the same IRQ. This is a standard issue with the PC architecture. A better solution is to simply use interrupts other than 3 or 4 for additional serial ports.

## 6 Digital I/O

### 6.1 DIO1 Header

The DIO1 port provides +5V, GND, and 12 digital I/O lines that may be used to interface the TS-2200 with a wide range of external devices. Additional digital I/O is available on the DIO2 header. These signals are connected directly to the 386EX and several have multiple functions. For example, DIO pins 6, 11, 12, and 13 are by default IRQ7, IRQ3, IRQ4, and IRQ5 respectively. By setting configuration registers in the 386EX, these pins can be individually changed to general purpose I/O (GPIO) as high-impedance inputs, open-drain outputs, or complementary outputs. Note that these same signals are also connected directly to the PC/104 bus; if a pin is configured as GPIO, then the associated IRQ will not be available for PC/104 expansion cards.

P3.2	14	13	IRQ5 / P3.3
IRQ4 / P3.0	12	11	IRQ3 / P3.1
DTR2 / SRXCLK	10	9	RI2 / SRXD
DSR2 / STXCLK	8	7	RTS2 / STXD
IRQ7 / P3.5	6	5	P1.0
P1.5	4	3	P3.6
GND	2	1	5V

Figure 2 – DIO1 Header Pinout

DIO pins 7-10 can be configured as a synchronous serial port supporting baud rates to 6.25Mbaud. These pins are COM2 handshake lines by default that can be also used as GPIO.

DIO pins 3, 4, 5, and 14 are always GPIO – they do not have secondary functions.

All digital outputs can source or sink up to 8mA. All digital inputs have standard TTL level thresholds.

For further information on configuration and use of these pins, **See Appendix G**.

### 6.2 DIO2 Header

Up to 13 additional DIO lines are available on the DIO2 Header. Pins 1,3,5, and 7 are digital inputs with 10K Ohm pull-up resistors that can be read at I/O location 77h bits 1-4. Pin 4 is a Digital output that drives the TS-2200 LED. Pins 6,8,13, and 14 are i386EX programmable I/O lines. Pin 10 is a fixed input that can be read (inverted polarity) at the COM2 Status Reg. (I/O location 2FEh bit 7). Pin 12 is the signal that enables the RS-485 Transmit driver. If the RS-485 option is not installed, this pin can be read as input at I/O location 77h bit 0. Pins 9 and 11 are open-drain active-low outputs that drive the Ethernet Link and LAN LEDs. The default configuration is for these to be driven by the Ethernet controller to indicate network presence and activity. These can be reprogrammed to be general-purpose outputs. For more information regarding these 2 lines, please consult the Cirrus Logic CS8900A Users Guide in Appendix H.

P1.3	14	13	IRQ6 / P3.4
TX485EN	12	11	LinkLED#
DCD2	10	9	RxLED#
RTS1 / P1.1	8	7	IN1@77
P1.2	6	5	IN2@77
LED-ON	4	3	IN3@77
GND	2	1	IN4@77

Figure 3 – DIO2 Header Pinout

Note – DIO2 pin 14 (P1.3) is also shared with user jumper JP3. If user jumper JP3 is being used, then DIO2 pin 14 should be left not connected.

For further information on configuration and use of these pins, **See Appendix G**.

## 7 LCD Interface

A 14-pin LCD connector is provided on the TS-2200 for interfacing with standard alphanumeric LCD displays. These displays use a common controller, the Hitachi HD44780 or equivalent. While software written for the HD44780 will work with all displays using the controller, the cable needed is dependent on the display used. For most displays, a straight-through type ribbon cable can be used. The connector on the LCD display is typically mounted on the backside of the display. **Warning** – using an incorrect cable or mounting the LCD connector on the front-side can result in a reverse power polarity and can damage the LCD display. Please refer to your LCD data sheets for in-depth information.

The TS-2200 BIOS incorporates a fairly complete set of INT10h video routines that work with the LCD.

Pin	Function	Comments
1	LCD 5V	
2	LCD GND	
3	Reg. Select	Buffered A0
4	Bias	470 Ohm to GND
5	LCD Enable	Active high
6	Write#	Active low
7	D1	
8	D0	
9	D3	
10	D2	
11	D5	D0 – D7: Buffered bi-directional data bus
12	D4	
13	D7	
14	D6	

Table 5 - LCD Header Signals

Once the LCD has been enabled (**INT15h/Func B042h** – see 0 below) the LCD can be written to using the standard BIOS routines. This includes the majority of PC languages, such as C and C++. See the programs included on the utility disk for examples.

2	4	6	8	10	12	14
1	3	5	7	9	11	13

Figure 4 - LCD Header Pinout

I/O addresses **72h** and **73h** are used to access the LCD. Figure 4

shows the header pin-out, while Table 5 lists the LCD signals. The section below will briefly describe the LCD interface signals.

The register select signal is simply the buffered A0 address line. Thus, reads and writes to **72h** cause register select to be low, and those to **73h** cause it to be high. Generally the LCD uses this line to separate data bytes from command bytes. See your LCD data sheet for details.

The /Write signal is an active low write enable line.

LCD Select is an active high signal, raised whenever the LCD addresses are being read or written.

D0 – D7 are bi-directional, buffered copies of the data bus and carry all data and commands to the LCD.

Table 4 is not the standard pin-outs given for LCD displays. But this pin-out allows a standard ribbon cable to be used when the ribbon cable is attached to the backside of the LCD.

## 8 10Base-T Ethernet Port

The TS-2200 has full-function IEEE 802.3 Ethernet capability (10 Mbit/sec) provided by a Cirrus Logic CS8900A Ethernet controller. The CS8900A is a single-chip, 16-bit Ethernet controller that includes such features as full-duplex operation, power saving shutdown modes, and LED indicators for link status and activity. The physical interface is 10Base-T (RJ45 connector).

The TS-2200 has both a LINK LED and a LAN LED that indicates the current ethernet status. The LINK LED (labeled D4) is active when valid ethernet link pulses are detected. This LED should be ON whenever the TS-2200 is powered on and properly connected to a 10BaseT Ethernet network. The LAN LED (labeled D3) should pulse ON briefly when any network traffic is detected. This includes all traffic, not just that sent to or from the TS-2200. Both of these LEDs are controlled by the CS8900A and do not require initialization. Additionally, the LEDs can be placed under software control, allowing the customer application use of the LEDs for feedback. Please see the CS8900A User Manual, Appendix H, for further details.

A standard packet driver is installed on the board by default, along with a few sample network applications written with the public domain Waterloo TCP/IP software (WATTCP). WATTCP is a freely available package (including source code) that provides TCP/IP connectivity for programs written for the DOS environment.

During POST, the BIOS initializes the CS8900A registers with the correct settings – interrupt IRQ12, I/O address range 300h – 30Fh, and I/O mapped operation. The DOS packet driver is loaded by AUTOEXEC.BAT once DOS starts. To run the sample programs (ping and finger) on the TS-2200, first examine the contents of the WATTCP.CFG configuration file in the A:\ETHERNET directory and correct any information that is not valid for your particular network. Then simply run a sample program from the DOS command line. For example:

```
[A:\]ping www.embeddedx86.com
Technologic Systems Example Configuration
Pinging 'www.embeddedx86.com' [209.130.84.83]
sent PING # 1 , PING receipt # 1 : response time 0.00 seconds

Ping Statistics
Sent      : 1
Received  : 1
Success   : 100 %
Average RTT : 0.35 seconds
[A:\]
```

If you prefer to use a package other than WATTCP, go right ahead. Device-drivers for other operating systems and network protocols are available from both the Technologic Systems and Cirrus Logic web sites (see Appendix H below).

## 9 Real Time Clock

---

The Dallas Semiconductor DS12887 is used for the PC compatible battery-backed real-time clock. It is a completely self-contained module that includes a Motorola 146818 compatible clock chip, the 32.768 kHz crystal, the lithium battery, and 114 bytes of battery-backed CMOS RAM. It is guaranteed to maintain clock operation for a minimum of 10 years in the absence of power. It is located at the standard PC I/O addresses of Hex 070 and 071. The top 32 bytes (index 60h through 7Fh) are not used by the BIOS and are available for user applications.

## 10 Watchdog Timer

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The Intel 386EX contains a 32-bit watchdog timer (WDT) unit that can be used in two different modes to effect a watchdog supervisory function. In either mode, a system reset is asserted when the WDT times out preventing a system “hanging” due to a software bug. To prevent a WDT timeout, the application must periodically “feed” the WDT by writing to specific I/O locations. The 32-bit down-counter allows timeout values as high as 160 seconds.

The general-purpose timer mode is more flexible in that the timeout values can be changed dynamically and the timer can be turned on and off under software control. The disadvantage of this mode is that it doesn't provide 100% protection because a bug could turn off the timer during a crash and the system would hang.

The software secure watchdog mode utilizes a “lockout sequence” to set a WDTEN bit in the watchdog status register. Once this bit is set, only a system reset can clear this bit. When WDTEN is set, it is not possible to change the WDT timeout value or to turn off the WDT. This provides a high level of assurance against errant software causing a system to hang.

For details see the Intel 386EX User Manual.

## 11 LED and Jumpers

The TS-2200 has three LEDs available for user software. The user LED (labeled D2) can be used for diagnostics, status messages, and simple output. This signal is also available as a digital output on the DIO2 port. When power is first supplied to the TS-2200, the user LED is immediately turned on under hardware control. Once the processor begins execution, the LED is turned off, then flashed on and off again briefly. After boot, this LED is reserved solely for user applications.

LEDs D3 and D4 are controlled by the CS8900A Ethernet Controller, and provide feedback on the status of the network. See Section 8 above for details.

If the user LED does not turn on at all when power is applied, the most likely problem is the power supply. Check that the +5V and GND connections are not reversed. A diode protects the board against damage in such a situation, but it will not run.

BIOS interrupt functions are used to interface software with the user LED and option jumper JP3. Please see Appendix C for further details and the utility disk for example code.

## 12 PC/104 Bus Expansion

The PC/104 is a compact implementation of the PC/AT ISA bus ideal for embedded applications. Designers benefit from using an already-developed standard, rather than creating their own. Further,

Pin #	Signal Name
A2 - A9	D7 through D0
A10	IOCHRDY
A11	EN
A12 - A31	A19 through A0
A32	GND
B1	GND
B2	RESETDRV
B3	+5V
B4	IRQ9
B11	SMEMW#
B12	SMEMR#
B13	IOW#
B14	IOR#
B20	SYSCLK (8.33 MHz)
B21	IRQ7 †
B22	IRQ6 †
B23	IRQ5 †
B24	IRQ4 †
B25	IRQ3 †
B28	BALE
B29	+5V
B30	OSC
B31	GND
B32	GND

Table 6 - Supported PC/104 Signals

† these signals are also connected to the DIO port.

the presence of a compact form-factor PC compatible standard has encouraged the development of a broad array of off-the-shelf products, allowing a very quick time to market for new products.

The electrical specification for the PC/104 expansion bus is identical to the PC ISA bus. The mechanical specification allows for the very compact implementation of the ISA bus tailor made for embedded systems. The full PC/104 specification is available from the IEEE Standards Office under # IEEE P996.1 (see Appendix E for further information). Basically, this bus allows multiple daughter boards in a 3.6 inch by 3.8 inch form factor to be added in a self-stacking bus. Since the electrical specs are identical (except for drive levels) to a standard PC ISA bus, standard peripherals such as COM ports, Ethernet, video, LCD drivers, and Flash drives may be easily added using standard drivers.

The TS-2200 implements a sub-set of the 8-bit version of the PC/104 bus. We have found this allows the support of the vast majority of PC/104 boards including all of the above mentioned examples. The one feature missing is DMA, which few PC/104 boards use.

See Appendix A for information on PC/104 pin numbering

Pin #	Signal Name
A1	IOCHCHK#
B5	-5V
B6	DRQ2
B7	-12V
B8	ENDXFR#
B9	+12V
B15	DACK3# ‡
B16	DRQ3 ‡
B17	DACK1#
B18	DRQ1
B19	REFRESH#
B26	DACK2#
B27	TC

Table 7 - Unsupported PC/104 Signals

‡ PC/104 expansion cards must not connect to these pins.

## 13 Loading, Executing and Debugging Programs

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Two methods are available for transferring files between a desktop PC and your TS-2200: Zmodem downloads, and Manufacturing Mode. Full descriptions of each are detailed below.

To make your program automatically execute at power up, just edit the AUTOEXEC.BAT file on the Flash SSD drive and replace the name of the factory test program (EPC-DIAG.EXE) with yours.

### 13.1 Zmodem Downloads

Using the Zmodem protocol to send files to and from the TS-2200 is simple and straightforward. The only requirement is a terminal emulation program that supports Zmodem, and virtually all do. If you are using Windows 9X for your development work, the HyperTerminal accessory works well.

To download a file to the TS-2200 from your host PC, execute `DL.BAT` at the DOS command line on the TS-2200 (while using console-redirection from within your terminal emulator) and begin the transfer with your terminal emulator. In HyperTerminal, this is 'Send File...' from the 'Transfer' menu.

To upload a file from the TS-2200 to your host PC, execute `UL.BAT <FILENAME>` at the DOS command line on the TS-2200 and start the transfer in your terminal emulator. Many emulators, HyperTerminal among them, will automatically begin the transfer themselves.

Occasionally there may be errors in transmission due to background solid state disk operations. This is not a problem -- Zmodem uses very accurate CRC checks to detect errors and simply resends bad data. Once the file transfer is complete the file is completely error free.

**Please note that** the utility used to perform Zmodem file transfers on the TS-2200 side is called DSZ, produced by Omen Technologies. **DSZ is shareware -- it is not free.** If you decide to use it, you are legally obligated to pay Omen Technologies. Currently the cost is \$20. Further info is available in the DSZ zip file located on the utility disk, and contact info for Omen Technologies is in Appendix E.

### 13.2 Manufacturing Mode

The TS-2200 has a special feature called 'Manufacturing Mode' which makes the on-board Flash SSD appear as just another drive on your desktop computer using a DOS device driver and a serial cable.

First, connect a null modem cable between COM2 on the TS-2200 and COM1 or COM2 of your desktop computer. Next, the TS-2200 must be placed in Manufacturing Mode. To do so, install jumper **JP1** and power cycle the unit. Manufacturing Mode will automatically start once the POST routines have been executed. At this point, the TS-2200 will simply sit and wait for serial packets to arrive from a host.

Now install the Manufacturing Mode driver on your desktop computer. To do so, simply copy the `MFGDRV.SYS` device driver from the utility disk to anywhere on your desktop machine's hard drive. Then insert the following line in your `CONFIG.SYS` file and reboot:

```
DEVICE=<PATH>\MFGDRV.SYS /UNIT=0 /BAUD=38K /PORT=COMX
```

Where `<PATH>` is the full path to the location where you copied the `MFGDRV.SYS` driver, and `X` is the port on your host PC that the null modem cable is connected to (1 or 2).

The Flash SSD drive should now appear on the next free drive letter on your desktop computer (usually the D: or E: drive). Simply copy your program onto the drive, and that's it!

You can create directories, edit files, and even execute programs on your desktop computer over the Manufacturing Mode link just the way you would with a regular disk drive, just a bit more slowly.

When you are finished, turn off the TS-2200, remove the jumper, and turn it back on. Your program will now execute every time the TS-2200 is turned on.

While Manufacturing Mode is in operation, the board LED provides feedback. While idle, the LED will cycle on and off at approximately 1/2 Hertz. While data is being transferred, it will cycle much more rapidly (anywhere from 5 to 1000 Hertz)

**NOTE:** The Manufacturing Mode driver currently does **not** work correctly with Windows 9X (95/98). Please use the Zmodem method if you are using Windows 9X.

### 13.3 Integrated BIOS Debugger

To provide simple, direct access to the TS-2100 hardware, the system BIOS has an integrated debugger that can perform standard low-level debugger functions. The debugger allows you to perform operations such as disassemble code, display and alter the contents of memory, write to and read from I/O ports, and single-step through or breakpoint code. The debugger is not intended for use as the only debugging tool for applications, but it can be a real lifesaver when you need interactive, direct access to hardware.

The BIOS debugger can be entered by any of several methods:

- The debugger hooks the CPU exception vectors in case a divide by zero occurs, an invalid opcode is executed, or an INT 3 instruction is executed, for example. By placing an INT 3 instruction in your application code the debugger will automatically be invoked. To resume, type the 'G' command to "GO", or continue on with the rest of initialization.
- From DOS-ROM by typing 'INT3' at the command prompt. If the full command.com interpreter is running, this is an internal command. If only mini-command.com is running, this will execute a small utility that simply contains an 'INT 3' instruction.
- From the BIOS Setup main menu (started by typing 'ctrl-C' during the BIOS POST), the **ENTER SYSTEM BIOS DEBUGGER** selection will enter the debugger. After use, typing the 'G' (go) command will return to the SETUP screens.
- As a boot action, as a last-ditch effort if the operating system cannot be booted from the appropriate drives or out of ROM.

A complete discussion of debugger commands is available in the Integrated BIOS Debugger Reference Manual, included on the TS-2100 Utility Disk and also available from the Technologic Systems web site. Entering '?' will list all available commands, and a 'g' (go) will return execution to the point where the debugger was called.

## 14 Video, Keyboard, and Console Redirection

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The TS-2200 has no video controller or keyboard interface. This was done to keep the board size small and the cost low. For applications that require it, a PC/104 video board can be added to the system easily. This could be a VGA controller, graphic LCD interface, or a custom board of your own design.

Without a video board in the system, the TS-2200 redirects all console activity to the COM2 serial port. Simply connect an ANSI terminal (or emulator) to COM2 with a null modem cable, using serial parameters of 9600 baud, 8 data bits, no parity, 1 stop bit, and make sure jumper **JP2** is installed. All text information that would normally be displayed on a video screen is now displayed in your terminal window, and any serial data sent to the TS-2200 is seen as standard keyboard input by programs.

Please note that the console redirection support is limited by the fact that there is no actual video or keyboard hardware on the TS-2200. Programs must use the standard BIOS routines for display and keyboard input, which are rerouted to the serial port. Any program that accesses the video or keyboard hardware directly will not work. Keyboard redirection is limited simply because most of the extended keys on the keyboard (function keys and Alt key in particular) are not sent by the terminal emulator. For these reasons, the console redirection feature is meant more for system development, testing, and field repair, rather than as the primary user interface for a finished product.

If your application uses COM2, removing the jumper **JP2** easily disables console redirection.

If you wish to use a different serial port and / or baud rate for the console, the `CONSOLE.EXE` utility allows these modifications to be made. Please see the appropriate application notes for further details, available on the utility disk or from the Technologic Systems web site.

If a video board is installed on the PC/104 bus, the video BIOS on the graphics card will automatically replace the standard video routines (INT10h), disabling both the LCD display and the display redirection (keyboard redirection will continue). If the console redirection jumper **JP2** is also removed, the keyboard redirection is disabled as well.

## **15 Feedback and Updates to the Manual**

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To help our customers make the most of our products, we are continually making additional and updated resources available on the Technologic Systems web site. These include manuals, application notes, programming examples, and updated software and firmware. Check in periodically to see what's new!

When we are prioritizing work on these updated resources, feedback from customers (and prospective customers) is the number one influence. If you have questions, comments, or concerns about your TS-2200 Embedded PC, *please let us know*. Details for contacting us are listed in the front of this manual.



## Appendix A - Board Diagram and Dimensions

Currently not available

## Appendix B - JP Jumper Block

Table 8 lists all option jumpers and their functions. These jumpers are clearly labeled on the upper edge of the board (see Appendix A above).

Jumper	Function
JP1	Manufacturing Mode
JP2	Console Redirection
JP3	User Jumper (P1.3)
JP4	TX485 Term. Res.
JP5	RX485 Term. Res.
JP6	Full Duplex RS-485
JP7	Half-Duplex RS-485

Table 8 - Jumper Listing

## Appendix C - System Memory Map

Resource	Starting Address		Size
	hex	decimal	
Extended Memory (RAM)			1M
BIOS (Shadow RAM)	100000h	1024k	
DOS / BIOS Extension (Shadow RAM)	F0000h	960k	64k
Solid-state disk drive window (Flash RAM)	E0000h	896k	64k
PC/104 or DiskOnChip	D0000h	832k	64k
PC/104 or Battery-Backed SRAM	CE000h	824k	8k
PC/104 (typically video BIOS)	C8000h	800k	24k
PC/104 (typically video BIOS)	C0000h	768k	32k
PC/104 (typically video memory)	A0000h	640k	128k
Lower Memory (RAM)	00000h	00000	640k

Figure 5 – TS-2200 Memory Map

## Appendix D - System I/O Map

The following table lists the I/O addresses used by the system. All other I/O locations from 100h through 3F7h are available on the PC/104 expansion bus.

Hex Address	Resource
F000h - FFFFh	Internal 386EX Registers
400h - EFFFh	PC/104 Bus (Not recommended for use)
3F8h - 3FFh	COM1
300h - 30Fh	CS8900A Ethernet controller
2F8h - 2FFh	COM2
80h - FFh	Internal 386EX peripherals
074h - 077h	Board configuration registers
072h - 073h	Alphanumeric LCD
070h - 071h	RTC and CMOS memory
000h - 06Fh	Internal 386EX peripherals

Table 9 – TS-2200 I/O Map

I/O Address	R / W	Bit 0 Description
74h	Read	Always 1
75h	Read	SRAM option 0 = Not installed 1 = Option installed
76h	Read	RS-485 option 0 = Not installed 1 = Option installed
76h	Write	RS-485 control 0 = use RTS enabled RS-485 1 = enable automatic RS-485
77h	Read	Returns status of TX485EN pin

Table 10 – TS-2200 Control Registers – All signals are R/W through bit 0 of the address

## Appendix E - BIOS Interrupt Functions

We have extended the standard BIOS interrupts with several functions that simplify interfacing with the TS-2200 hardware.

Many books are available with detailed information on using interrupts with just about any language. Example code is also available on the utility disk.

### ***Int 15h / Function B000h - Technologic Systems BIOS information***

This function is mostly for our own internal use, but may be useful for user programs as well. For example, your program could have debugging code that executes on your desktop machine, but does not when the program is executing on the TS-2200.

**ENTRY:**

**AX = B000h**

**EXIT:**

**CY = 0** (carry flag)

**AH = 0**

**AL = SP\_VERSION**

For standard versions of the BIOS, this is **0**. An 'SP number' is assigned when custom modifications are made to the BIOS for a client, and it is returned in this register. Contact us for further information.

**BH = BIOS Version, Major Number.**

E.g. If the current BIOS version is 1.25, the register will contain **01h**.

**BL = BIOS Version, Minor Number.**

E.g. If the current BIOS version is 1.25, the register will contain **19h** (19h = 25 decimal).

**CH = Base Flash Memory Size / 512kB**

The TS-2200 is available with 1024kB of base Flash memory standard, but this can be increased to 2048 KB for custom orders. These would be returned as **02h** or **04h**, respectively.

**CL = 16h**

This is the hardware model number (16h = 22 decimal).

**DX = 'TS' (5452h)**

**Int 15h / Function B010h - LED Control**

This function is used to turn the board LED on and off. You can also invert the LED, i.e. if the LED is off, it will be turned on, and if it is on it will be turned off.

**ENTRY:**

**AX = B010h**  
**BH = 00** - LED off.  
**01** - LED on.  
**81** - LED invert.

**EXIT:**

**CY = 0** (carry flag)  
**AH = 0**

**Int 15h / Function B042h – Alphanumeric LCD Support**

This routine enables and disables the console on the LCD interface. It supports all LCD displays sized 2 x 40 or smaller using a Hitachi HD44780 controller.

**ENTRY:**

**AX = B042h**  
**BH = 00** - Disable LCD  
**01** - Enable LCD  
**02** - Return current LCD status

**EXIT:**

**CY = Set if error, else clear if success.** (carry flag)  
**AH = 00** - No Error / LCD initialized OK  
**BH = 00** - LCD currently disabled / Not present  
**01** - LCD currently enabled and running.

**Appendix F - Using A 12.5 MHz Baud Clock**

Each serial port baud rate generator clock can be independently switched between either the standard 1.85 MHz clock or a 12.5 MHz clock (the internal processor clock divided by 2).

Changing the clock to 12.5 MHz allows baud rates higher than 115 kbaud (up to 781 kbaud), as well as low error, non-standard lower baud rates (such as 24 kbaud).

The baud rate clock is controlled by I/O location 0F836h:

Bit 0 controls COM1.  
 Bit 1 controls COM2.

Setting a bit to 0 uses the standard 1.85 MHz clock, and setting a bit to 1 uses the 12.5 MHz processor clock. **NOTE:** You **must not** modify the other bits of this register. You **must** use a read-modify-write procedure to change these bits. The following example in assembly illustrates this:

```
MOV  DX, 0F836          ; load the I/O address
IN   AL, DX            ; read the configuration register
OR   AL, 00000001b     ; switch COM1 to the 12.5 MHz clock
OUT  DX, AL            ; write the register
```

**Note:** If using automatic RS-485, see section 5.4 above.

## Appendix G - Direct Control of the 386EX DIO Pins

The Intel386 EX processor has three 8-bit bi-directional I/O ports, all of which are functionally identical (Figure 16-1). Each port has three control registers and a status register. All three ports share pins with internal peripherals. Several of these pins are routed to the DIO ports. If your design does not require a pin's peripheral function, you can configure that pin for use as an I/O port. For example, if you don't need IRQ6 for PC/104, you can use the associated pin (386EX P3.4) as DIO2 pin 13. Each pin can operate either in I/O mode or in peripheral mode. In I/O mode, a pin has three possible configurations:

- high-impedance input
- open-drain output (requires an external pull-up resistor)
- complementary output

In I/O mode, register bits control the direction (input or output) of each pin and the value of each output pin. In peripheral mode, the internal peripheral controls the operation (input or output) of the pin.

Each port has three control registers and a status register associated with it (). The control registers (PnCFG, PnDIR, and PnLTC) can be both read and written. The status register (PnPIN) can only be read. All four registers reside in I/O address space.

Register	I/O Address	Description
P1CFG P3CFG (read/write)	0F820h 0F824h	Port n Mode Configuration: Each bit controls the mode of the associated pin. 0 = Selects I/O mode. 1 = Selects peripheral mode.
P1DIR P3DIR (read/write)	0F864h 0F874h	Port n Direction: Each bit controls the direction of a pin that is in I/O mode. If a pin is in peripheral mode, this value is ignored. 0 = Configures a pin as a complementary output. 1 = Configures a pin as either an input or an open-drain output.
P1LTC P3LTC (read/write)	0F862h 0F872h	Port n Data Latch: Each bit contains data to be driven on to an output pin that is in I/O mode. Write the desired pin state value to this register. If a pin is in peripheral mode, this value is ignored. Writing a value to a PL bit causes that value to be driven onto the corresponding pin. For a complementary output, write the desired pin value to its PL bit. This value is actively driven high or low onto the pin. For an open-drain output, a zero results in a actively driven low on the pin, a one results in a high-impedance (input) state at the pin. To configure a pin as an input, write a one to the corresponding PL bit. A one results in a high-impedance state at the pin, allowing external hardware to drive it. Reading this register returns the value in the register – not the actual pin state.
P1PIN P3PIN (read only)	0F860h 0F870h	Port n Pin State: Each bit of this read-only register reflects the state of the associated pin. Reading this register returns the current pin state value, regardless of the pin's mode and direction.

Table 11 – 386EX I/O Port Registers

In the default configuration, P1.5, P1.0 and P3.6 are all initialized as inputs, while P3.0, P3.1, and P3.3 are initialized as "peripherals" (IRQ4, IRQ3, and IRQ5)

**Warning: When changing these registers, always use read/modify/write procedures so that other port pins (used by on-board peripherals) are not affected.**

For example, let's say you want to use 386EX Port 3.1 (DIO1 pin 11) as an output rather than IRQ3 (the default configuration).

1. Read P3CFG (I/O F824h), AND it with 0FDh, write it back to F824h. (changes from peripheral to I/O pin)
2. Read P3DIR (I/O F874h), AND it with 0FDh, write it back to F874h. (this made it a complementary output)
3. To set this pin to a "1", Read P3LTC (I/O F872h), OR it with 02h, write it back.

Note: Because the serial ports are internal to the 386EX, COM1 and COM2 can still use IRQ4 and IRQ3 even when the associated pins P3.1 and P3.0 are configured as DIO pins DIO1.11 and DIO1.12 – the interrupts are simply no longer available on the PC/104 bus.

## Appendix H - Further References

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### Technologic Systems Web Site

<http://www.embeddedx86.com/>

Crystal CS8900A Ethernet Controller Overview

<http://www.cirrus.com/products/overviews/cs8900a.html>

Dallas Semiconductor DS12887 Data Sheet

Intel 386EX User's Guide

<http://developer.intel.com/design/intarch/manuals/272485.htm>

Maxim Integrated Products

<http://www.maxim-ic.com/>

National Semiconductor NS16C450 Data Sheet

Omen Technologies

<http://www.omen.com/>

PC/104 Consortium Web Site

<http://www.pc104.org/>

Waterloo TCP/IP Software (WATTCP)

<http://www.wattcp.com/>

## Appendix I - Manual Revisions

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- |          |                                               |
|----------|-----------------------------------------------|
| 11/06/00 | • updated URL to Waterloo TCP/IP homepage     |
| 11/02/00 | • updated URL to Intel 386EX User's Guide     |
|          | • updated System I/O map                      |
| 07/22/99 | • Added info on the integrated BIOS Debugger  |
|          | • Describe ethernet LEDs                      |
|          | • Changed Appendix E to mention 2048 KB Flash |
| 07/21/99 | • Rewrote Appendix G                          |
|          | • Corrected minor errors                      |
| 07/20/99 | • New Manual                                  |